

Stability of a Nonlocal Traffic Flow Model for Connected Vehicles

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Main Message

- ▶ Traffic flow of connected vehicles can be modeled by nonlocal conservation laws.
- ▶ Improper use of nonlocal information in the vehicle velocity selection could result in persistent traffic waves.
- ▶ To utilize the benefits of vehicle connectivity, nearby information should deserve more attention.

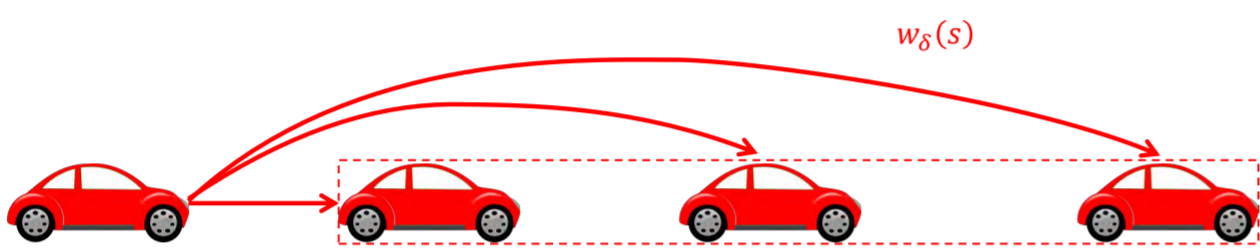
Modeling Traffic Flow: Non-Connected to Connected



LWR (1956)^{1,2}:

$$\partial_t \rho(x, t) + \partial_x (\rho(x, t) U(\rho(x, t))) = 0.$$

- ▶ $\rho(x, t)$: traffic density;
- ▶ $u(x, t) = U(\rho(x, t))$: traffic velocity;
- ▶ Capture shock waves (traffic jams).



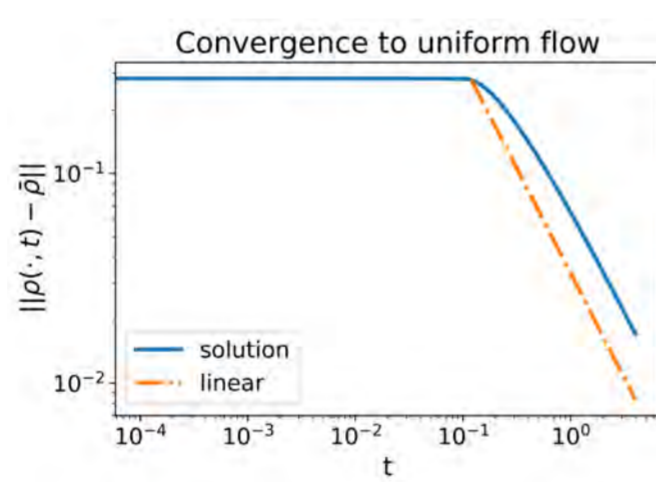
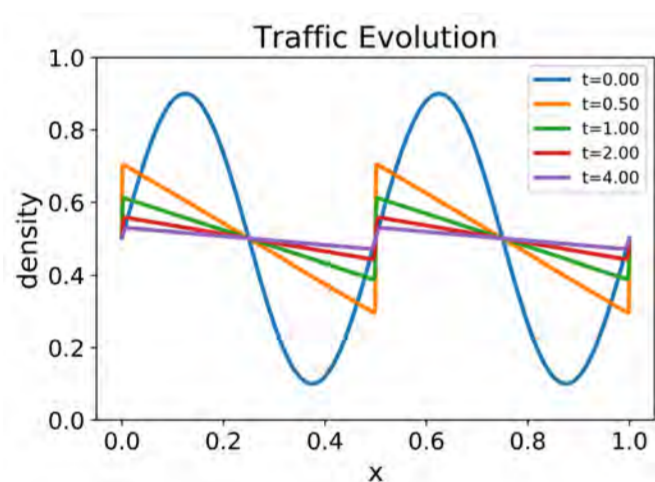
Nonlocal LWR (2016)³:

$$\partial_t \rho(x, t) + \partial_x \left(\rho(x, t) U \left(\int_0^\delta \rho(x+s, t) w_\delta(s) ds \right) \right) = 0.$$

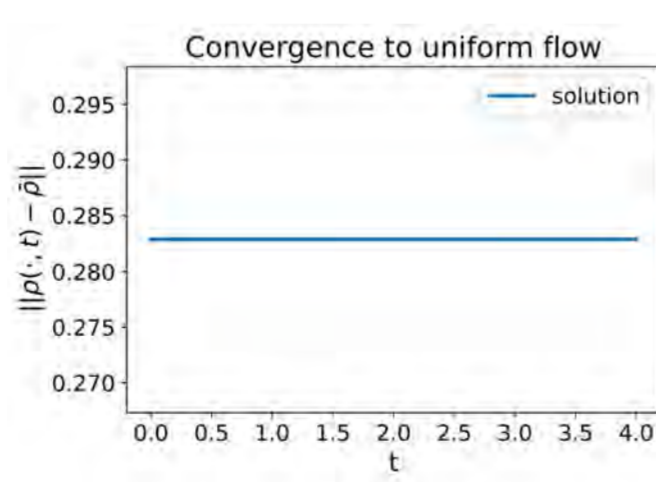
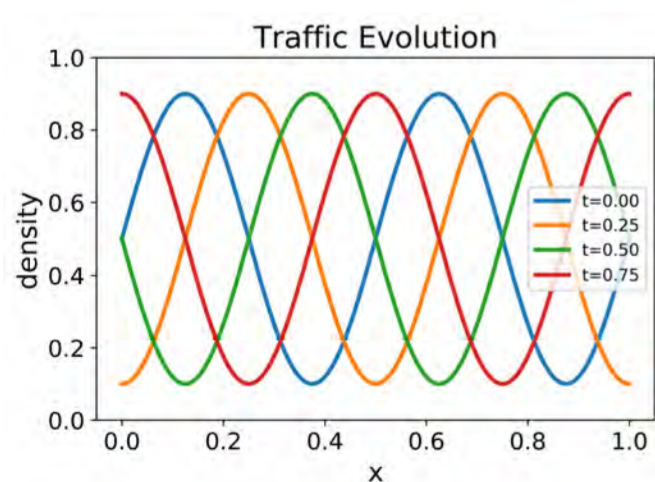
- ▶ $\int_0^\delta \rho(x+s, t) w_\delta(s) ds$: nonlocal traffic density;
- ▶ $w_\delta(s)$ characterizes how nonlocal information is used;
- ▶ This is a nonlocal conservation law.

Connectivity: Benefit or Drawback

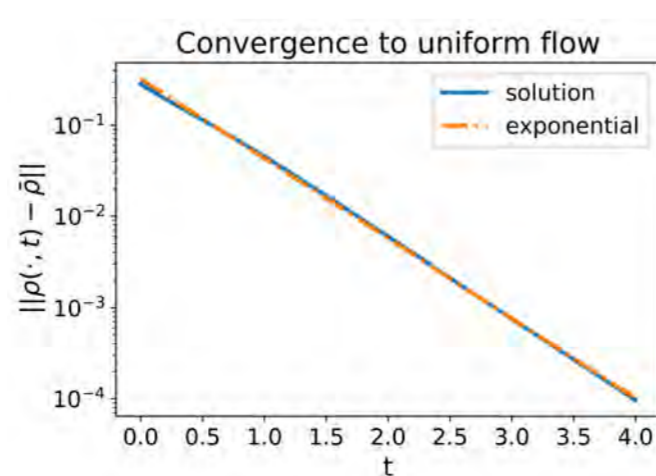
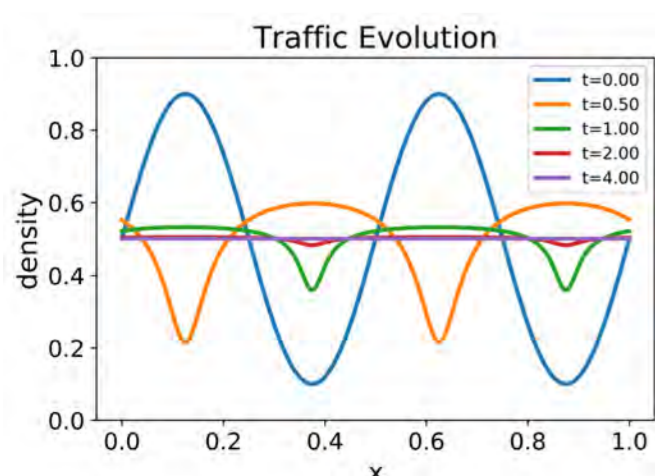
- ▶ Set $U(\rho) = 1 - \rho$, $\rho_0(x) = 0.5 + 0.4 \sin(4\pi x)$.
- ▶ Local LWR:



- ▶ Nonlocal LWR with $w_\delta(s) = \frac{1}{\delta}$:



- ▶ Nonlocal LWR with $w_\delta(s) = \frac{2}{\delta^2}(\delta - s)$:



Global Stability Theorem

Under the following assumptions:

- ▶ All vehicles drive on a ring road (periodic boundary condition);
- ▶ The velocity function is linear: $U(\rho) = 1 - \rho$;
- ▶ The nonlocal kernel $w_\delta(s)$ is C^1 smooth, non-negative, **non-increasing and non-constant**;
- ▶ The initial density satisfies $0 < \rho_{\min} \leq \rho(x, 0) \leq \rho_{\max} \leq 1$;

and suppose $\rho(x, t)$ is the solution of the nonlocal LWR model, $\bar{\rho}$ is the average density. Then there exists a constant $\lambda > 0$ that only depends on the nonlocal range δ and nonlocal kernel $w_\delta(s)$, such that:

$$\|\rho(\cdot, t) - \bar{\rho}\|_{L^2} \leq e^{-\lambda t} \|\rho(\cdot, 0) - \bar{\rho}\|_{L^2}, \quad \forall t \geq 0.$$

As a corollary, **the traffic density $\rho(\cdot, t)$ very quickly converges to the uniform flow $\bar{\rho}$ as $t \rightarrow \infty$.**

Key Ingredients

- ▶ The model can be rewritten as:

$$\partial_t \rho(x, t) + \partial_x (\rho(x, t) (1 - \rho(x, t))) = \nu(\delta) \partial_x (\rho(x, t) \mathcal{D}_x^\delta \rho(x, t)),$$

where \mathcal{D}_x^δ is the nonlocal derivative operator:

$$\mathcal{D}_x^\delta \rho(x, t) = \frac{1}{\nu(\delta)} \int_0^\delta [\rho(x+s, t) - \rho(x, t)] w_\delta(s) ds,$$

$$\nu(\delta) = \int_0^\delta s w_\delta(s) ds.$$

The nonlocal diffusion $\partial_x (\rho(x, t) \mathcal{D}_x^\delta \rho(x, t))$ can dissipate all traffic waves.

- ▶ Maximum principle:

$$\rho_{\min} \leq \rho(x, t) \leq \rho_{\max},$$

at any time $t \geq 0$.

- ▶ Define the energy functional as:

$$E(t) = \frac{1}{2} \int_0^1 (\rho(x, t) - \bar{\rho})^2 dx,$$

then:

$$\frac{dE(t)}{dt} = -\nu(\delta) \int_0^1 \rho(x, t) \partial_x \rho(x, t) \mathcal{D}_x^\delta \rho(x, t) dx.$$

- ▶ Nonlocal Poincaré inequality:

$$\int_0^1 \partial_x \rho(x, t) \mathcal{D}_x^\delta \rho(x, t) dx \geq \alpha \int_0^1 (\rho(x, t) - \bar{\rho})^2 dx,$$

α only depends on δ and $w_\delta(s)$.

- ▶ Nonlinear nonlocal Poincaré inequality:

$$\int_0^1 \rho(x, t) \partial_x \rho(x, t) \mathcal{D}_x^\delta \rho(x, t) dx \geq \rho_{\min} \int_0^1 \partial_x \rho(x, t) \mathcal{D}_x^\delta \rho(x, t) dx.$$

- ▶ Energy estimate:

$$\frac{dE(t)}{dt} \leq -\nu(\delta) \alpha \rho_{\min} E(t), \quad \forall t \geq 0.$$

Applying Gronwall's lemma yields exponential decay of $E(t)$.

References

- ¹ M.J.Lighthill, G.B.Whitham, On kinematic waves II: A theory of traffic flow on long, crowded roads. Proceedings of the Royal Society of London Series, 1955.
- ² P.I.Richards, Shock waves on the highway, Operations Research, 1956.
- ³ Goatin P, Scialanga S. Well-posedness and finite volume approximations of the LWR traffic flow model with non-local velocity. Networks & Heterogeneous Media, 2016

Further Information

- ▶ Paper submitted: Stability of a Nonlocal Traffic Flow Model for Connected Vehicles, with Q. Du. (<https://arxiv.org/abs/2007.13915>)
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